## Solving Reachability Problems with SAT

April 13, 2023

#### Outline

### Modeling Systems with Boolean Formulae

Kripke Structure Boolean (Propositional) Encoding of States

#### **Bounded Model Checking**

Basic Ideas

A Maze Solving Game

### Kripke Structure

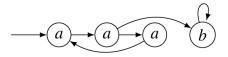
In model checking we typically model our target entity with Kripke structures.

### Definition (Kripke Structure)

A Kripke structure M is a five-tuple  $M = (S, S_0, R, AP, L)$ 

- 1. S is a set of states
- 2.  $S_0 \subseteq S$  is the set of initial states
- 3.  $R \subseteq$  is a transition relation
- 4. AP is the set of atomic propositions
- 5.  $L \to 2^{AP}$  is a function that labels each state with the set of those atomic propositions that are true in that state

# Kripke Structure (continued)



For example, this Kripke structure has:

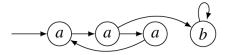
- 1.  $S = \{s_1, s_2, s_3, s_4\}$ , counting from left to right
- 2.  $S_0 = s_1$
- 3.  $R = \{(s_1, s_2), (s_2, s_3), (s_2, s_4), (s_3, s_1), (s_4, s_4)\}$
- 4.  $AP = \{a, b\}$
- 5. L(x) = a, for  $x \in \{s_1, s_2, s_3\}$ , L(x) = b for  $x \in \{s_4\}$

### Definition of Reachability Problem

▶ Given a Kripke Structure M, can we reach some state  $s_i$  in some  $n \in \mathbb{N}$  steps of transition from a initial state  $s_0 \in S_0$ ?

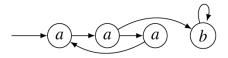
## Boolean (Propositional) Encoding of States

Our objective: Encode a reachability problem on Kripke structure to a boolean formula whose satisfiability can be tested by a SAT solver.



- For each state, assign a boolean word to them
- For example,  $s_1 = 00$ ,  $s_2 = 01$  and so on
- For each bit in the word, create a variable  $v_i$
- Now we can represent the states with bits, e.g.  $s_1 := \neg v_0 \land \neg v_1$  and  $s_2 := \neg v_0 \land v_1$

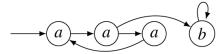
# Boolean (Propositional) Encoding of States (continued)



- We denote the next state by appending a apostrophe symbol to the original variable name, for example,  $v_0'$  and  $v_1'$
- For initial state  $S_1$ , we can encode the initial state set  $S_0$  as a boolean function  $S_0(v_0, v_1) = \neg v_0 \wedge v_1$
- ▶ Every transition (arrow) can be represented by a formula in the form of  $T_{s_1 \to s_2} = s_1 \land s_2 = \neg v_0 \land \neg v_1 \land \neg v_0' \land v_1'$
- Transition function can be represented by disjunction of individual transitions, e.g.

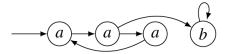
$$R(v_0, v_1, v_0', v_1') = T_{s_1 \to s_2} \lor T_{s_2 \to s_2} \lor T_{s_2 \to s_4} \lor T_{s_3 \to s_1} \lor T_{s_4 \to s_4}$$

## Modeling a Procedure with Multiple Steps of Transitions



- ► With the previously mentioned method, we can only model a one-step transition system
- But we want to know that whether a state can be reached in n steps of transition
- ▶ How do we model more steps?

## Modeling a Procedure with Multiple Steps of Transitions



- With the previously mentioned method, we can only model a one-step transition system
- But we want to know that whether a state can be reached in n steps of transition
- ► How do we model more steps?
- Answer: We can make multiple copies of the transition function!

## Bounded Model Checking

- ► For a two step transition system, we only have one copy of the transition function
- ▶ Recall that  $S_0 \wedge R(v_0, v_1, v'_0, v'_1)$  can represent the states that can be reached in one step of transition
- ► To make our formula shorter, we rewrite  $R(v_0, v_1, v'_0, v'_1)$  as R(V, V')
- ightharpoonup R(V,V') is a word-level modeling of the transition function and denotes the transition from first step (V) to the second step (V')

## Bounded Model Checking (continued)

- Now we can make copies of the transition system by feeding different *V* values to the function *R*
- e.g. for three steps we can do  $S_0 \wedge R(V, V') \wedge R(V', V'') \wedge R(V'', V''')$
- If we want to know whether we can reach some state  $S_f$  in 3 steps, we can append  $s_f$  to the end of the conjunction:  $S_0 \wedge R(V, V') \wedge R(V', V'') \wedge R(V'', V''') \wedge S_f$
- ▶ Generalize to *n* steps:  $S_0 \land R(V_0, V_1) \land \cdots \land R(V_{n-1}, V_n) \land S_f$
- ► If SAT, then the model returned by SAT solver is the complete trace of transition
- ▶ If UNSAT, then  $S_f$  can not be reached in n steps

### Modeling a Maze Solving Game

We want to find a path from upper-left corner to the bottom-right corner of the maze.

### **Encoding Each State of a Maze**

- For a  $n \times n$  maze, obviously we have  $n^2$  states
- ► An easiest way to encode states is to assign each one of them a natural number
- ▶ e.g. for a state on row i and column j, assign value  $i \cdot n + j$  to it
- ▶ We define the numbering function  $N(i,j) = i \cdot n + j$

### **Encoding the Transition Function**

- ► For each maze cell, there are at most four states that can be reached (left, right, up, down)
- ▶ We can describe two connected state m, n by adding a clause  $N(i_m, j_m) \wedge N(i_n, j_n)$  where  $i_m, j_m$  and  $i_n, j_n$  are the coordinate of m and n accordingly
- ► The transition function will be:  $R(i,j,i',j') = \bigwedge_{m,n \in All \text{ Adjacent States}} N(i_m,j_m) \land N(i'_n,j'_n)$